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Integer Programming: Relaxations

Eduardo Camponogara

Department of Automation and Systems Engineering Federal University of Santa Catarina

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Introduction

Relaxations

Lagrangian Relaxation

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Summary

Introduction

Relaxations

Lagrangian Relaxation

- Optimality Conditions: How do we assess the quality of a given candidate solution with respect the optimum, without knowing the optimum?
- This can be achieved by solving easier problem to optimality, however within a space that includes the feasible space of the problem at hand.

- Optimality Conditions: How do we assess the quality of a given candidate solution with respect the optimum, without knowing the optimum?
- This can be achieved by solving easier problem to optimality, however within a space that includes the feasible space of the problem at hand.

Relaxations can be obtained by:

- disconsidering some constraints;
- neglecting the integrality of discrete variables;
- solving a simplified problem.

Take the following Integer Program:

$$IP: z = \max \{ c^{\mathrm{T}} x : x \in X \subseteq \mathbb{Z}^n \}$$

- Given a candidate solution x*, how can we prove that x* is an optimal solution?
- We look for optimality conditions that provide a stopping condition for algorithms.

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- Given a candidate solution x*, how can we prove that x* is an optimal solution?
- We look for optimality conditions that provide a stopping condition for algorithms.

- One method consists of finding a lower bound <u>z</u> ≤ z and an upper bound <u>z</u> ≥ z such that <u>z</u> = <u>z</u>, in which case z is the optimum.
- Typically, algorithm produce two sequences of bounds:
 - a sequence of upper bounds $\overline{z}_1 > \overline{z}_2 > \ldots > \overline{z}_t \ge z$
 - ▶ a sequence of lower bounds $\underline{z}_1 < \underline{z}_2 < \ldots < \underline{z}_k \leq z$.
- Given $\xi \ge 0$, we can define a stopping criterion such as $|\overline{z}_t \underline{z}_k| \le \xi$.

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 - ▶ a sequence of lower bounds $\underline{z}_1 < \underline{z}_2 < \ldots < \underline{z}_k \leq z$.
- Given ξ ≥ 0, we can define a stopping criterion such as |z_t − <u>z_k</u>| ≤ ξ.

- When an algorithm terminates, the conditions ascertain that the candidate solution z is at most ξ units worse than the optimum.
- The ability to estimate the quality of candidate solution is of fundamental importances in optimization.

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- The ability to estimate the quality of candidate solution is of fundamental importances in optimization.

Finding a feasible solution may be a hard or easy task. It is a problem dependent issue.

- Any feasible solution x, x ∈ X, induce a bound (lower bound for maximization) given that c^Tx ≤ c^Tx^{*} = z^{*}.
- For NP-Complete problems, the search for a feasible solution corresponds to solving the problem.
- On the other hand, finding a feasible route for the traveling salesman probllem is easy, the hardness being in reaching the shortest route.

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Dual Bound

- A method to find an upper bound relies on a relaxation of the problem at hand.
- That is, a simpler problem whose optimal solution has an objective value not inferior to the optimum of the problem of concern.

Dual Bound

Definition Relaxation problem *R*:

laxation problem A.

$$z^{ ext{R}} = ext{max} \; \{f(x) : x \in \mathcal{T} \subseteq \mathbb{R}^n\}$$

is a relaxation of the problem IP:

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z = \max \{ c(x) : x \in X \subseteq \mathbb{R}^n \}
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if:

i) $X \subseteq T$ ii) $f(x) \ge c(x)$ for all $x \in X$.

L Dual Bound

Dual Bound

Proposition IF (R) is a relaxation of (IP) then $z^{\rm R} \ge z$.

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Linear Relaxation

Linear Relaxation

For the integer programming problem:

 $\max \{ c^{\mathrm{T}} x : x \in P \cap \mathbb{Z}^n \}$

with formulation:

$$P = \{x \in \mathbb{R}^n_+ : Ax \le b\}$$

the linear relaxation is:

$$z^{\mathrm{PL}} = \max \{ c^{\mathrm{T}} x : x \in P \}$$

Linear Relaxation

Example

$$z = \max 4x_1 - x_2$$

s.t.: $7x_1 - 2x_2 \le 14$
 $x_2 \le 3$
 $2x_1 - 2x_2 \le 3$

where $x \in \mathbb{Z}_+^2$.

Lower bound: notice that $\underline{x}=(2,1)$ is feasible, therefore $z\geq$ 7.

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Upper bound: an optimal solution to the linear relaxation $x^* = \left(\frac{20}{7}, 3\right)$ with $z^{\text{LP}} = \frac{59}{7}$, thus one concludes that $z \le 8 \le \frac{59}{7}$, in which $8 = \lfloor \frac{59}{7} \rfloor$.

Linear Relaxation

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Combinatorial Relaxation

- When the relaxation consists of a combinatorial problem, the relaxation is said to be a combinatorial relaxation.
- An example of a combinatorial relaxations for the traveling salesman problem and the knapsack problem are given below.

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The Traveling Salesman Problem (TSP)

min $\sum_{i=1}^n \sum_{j=1}^n c_{ij} x_{ij}$ (1)n

s.t.:
$$\sum_{j=1} x_{ij} = 1$$
 $i = 1, .., n$ (2)

$$\sum_{i=1}^{n} x_{ij} = 1 \qquad j = 1, .., n \tag{3}$$

$$\sum_{i\in S}\sum_{j\notin S} x_{ij} \ge 1 \qquad \forall S \subset \{1,\ldots,n\}, |S| \ge 2$$
(4)

 $x_{ij} \in \{0,1\}$ $\forall (i,j) \in A$ (5)

The Traveling Salesman Problem

- Discarding the family (4) of constraints, the allocation problem is obtained.
- Notice that the allocation problem can be solved efficiently.

The Knapsack Problem

$$\begin{array}{ll} (\mathcal{KP}) & \max & \sum\limits_{j=1}^n c_j x_j \\ & \mathrm{s.t.:} & \sum\limits_{j=1}^n a_j x_j \leq b \\ & x_j \in \{0,1\}, j=1,\ldots,n \end{array}$$

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Combinatorial Relaxation

The Knapsack Problem

A first relaxation is obtained if we take the integers immediately inferior to the weights of the items:

$$(RP_1) \max \sum_{\substack{j=1\\j=1}^{n}}^{n} c_j x_j$$

s.t.:
$$\sum_{\substack{j=1\\j=1}}^{n} \lfloor a_j \rfloor x_j \le b$$

$$x_j \in \{0,1\}, j = 1, \dots, n$$
(6)

The Knapsack Problem

The above relaxation is equivalent to the problem:

$$(RP_2) \max \sum_{j=1}^{n} c_j x_j$$

s.t.:
$$\sum_{j=1}^{n} \lfloor a_j \rfloor x_j \le \lfloor b \rfloor$$

$$x_j \in \{0, 1\}, j = 1, \dots, n$$

$$(7)$$

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Lagrangian Relaxation: the Knapsack Problem

First, consider the general integer program given by:

$$\begin{array}{ll} (P) & z = & \max \ c^T x \\ & \mathrm{s.t.} : \ Ax \leq b \\ & x \in \mathcal{X} \subseteq \mathbb{Z}' \end{array}$$

As seen above, a relaxation is obtained if we neglect the constraints $\{Ax \leq b\}$.

Lagrangian Relaxation: Example

Rather than discarding $\{Ax \le b\}$, the Lagrangian relaxation introduced these constraints in the objective:

$$LR(u) \quad z = \max c^{T} x + u^{T} (b - Ax)$$

s.t.: $x \in \mathcal{X}$
 $u > 0$

Lagrangian Relaxation

Proposition

- Let $z(u) = \max \{ c^T x + u^T (b Ax) : x \in X \}.$
- Then $z(u) \ge z$ for all $u \ge 0$.

Lagrangian Relaxation: Remarks

- Given u ≥ 0, the optimal solution to (LR) induces an upper bound z(u) ≥ z*.
- We can verify that $z(u) \ge c^T x$, for all $x \in \mathcal{P} = \{x : x \in X \in Ax \le b\}$:
 - $c^T x \le c^T x + u^T (b Ax)$ since $b Ax \ge 0$, x is feasible, and $u \ge 0$;
 - Since the feasible solution to the integer program (P) are also within the feasible space of LR, we conclude that z(u) ≥ z*.

Lagrangian Relaxation: Remarks

- Given u ≥ 0, the optimal solution to (LR) induces an upper bound z(u) ≥ z*.
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 - $c^T x \le c^T x + u^T (b Ax)$ since $b Ax \ge 0$, x is feasible, and $u \ge 0$;
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Convexity of Dual Function

Take $u, v \ge 0$ and $\theta \in [0, 1]$. Then

$$z(\theta u + (1 - \theta)v) = \max_{x \in \mathcal{X}} c^{T}x + (\theta u + (1 - \theta)v)^{T}(b - Ax)$$

$$= \max_{x \in \mathcal{X}} c^{T}(\theta + (1 - \theta))x + (\theta u + (1 - \theta)v)^{T}(b - Ax)$$

$$= \max_{x \in \mathcal{X}} \theta[c^{T}x + u^{T}(b - Ax)] + (1 - \theta)[c^{T}x + v^{T}(b - Ax)]$$

$$\leq \theta \cdot \max_{x \in \mathcal{X}} [c^{T}x + u^{T}(b - Ax)] + (1 - \theta) \cdot \max_{x \in \mathcal{X}} [c^{T}x + v^{T}(b - Ax)]$$

$$= \theta z(u) + (1 - \theta)z(v)$$

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Lagrangian Dual

Since z(u) is an upper bound for z^* , naturally one would wish to minimize the upper bound, giving rise to the Lagrangian Dual:

$$\begin{array}{rcl} LD: & \min & z(u) & \cong & \min & \max & c^T x + u^T (b - Ax) \\ & u \geq 0 & & u \geq 0 \\ & & & \text{s.t.:} & x \in \mathcal{X} \end{array}$$

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Lagrangian Relaxation

Lagrangian Dual

- The Lagrangian dual is convex but not differentiable problem.
- An approximate solution for LD could be sought.
- Under certain conditions, an optimal solution can be found using the subgradient algorithm.

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Subgradient

Definition

Given a function $z : \mathbb{R}^n \to \mathbb{R}$, a vector $d(u) \in \mathbb{R}^n$ is a subgradient for z at $u \in U$ if:

$$z(v) \geq z(u) + d(u)^T(v-u), \forall v \in \mathcal{U}$$

in which \mathcal{U} is the domain of z.

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Subgradient

► Take u ≥ 0 for LD, and let x(u) ∈ X be the point that induces the value z(u).

▶ Then, a subgradient for *z* at *u* is given by:

d(u) = b - Ax(u)

because z(u) is a convex function in u.

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Subgradient Algorithm

- 1. Input parameters: $u_0 \ge 0$, μ_0 , and $\rho < 1$.
- 2. Let k = 0.
- 3. Compute $z(u_k)$ and obtain $x(u_k)$ by solving $LR(u_k)$.
- 4. If $x(u_k)$ is feasible for P, or stopping criteria is satisfied, then halt.
- 5. Let $d_k = b A_x(u_k)$ be the subgradient.
- $6. \quad u_{k+1} = u_k \mu_k d_k.$
- 7. $\mu_{k+1} = \rho \mu_k$, k = k + 1, and repeat from step 3.

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Lagrangian Dual as an LP Program

Example: Consider the following instance of the knapsack problem:

$$z = \max 10x_1 + 7x_2 + 25x_3 + 24x_4$$

s.t.: $2x_1 + x_2 + 6x_3 + 5x_4 \le 7$
 $x_1, x_2, x_3, x_4 \in \{0, 1\}$

Challenge: develop an LP program equivalent to the Lagrangian Dual.

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Challenge: develop an LP program equivalent to the Lagrangian Dual.

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Integer Programming: Relaxations

Thank you for attending this lecture!!!

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