

Linear Programming

Fundamentals, Algorithm Simplex and Duality

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Introduction

Simplex Algorithm

Initial Solution

Duality

Sumário

Introduction

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Initial Solution

Duality

History of Linear Programming

History

- ▶ Linear Programming was incepted in the 1930's, experience great advance in the 1940's with the development of the Smiplex Algorithm by George Dantzig.
- ▶ LP algorithms are rather efficient.
- ▶ Specially-tailored algorithms were proposed, particularly for network-flow problems.

History of Linear Programming

History

- ▶ In 1979, Khachiyan discovered the first polynomial-time algorithms, which became known as the ellipsoid algorithm.
 - ▶ It is not practical.
 - ▶ The ellipsoid algorithm has significant impacts on integer programming and in the solution of linear programming.

History of Linear Programming

History (continued)

- ▶ In 1984, Karmakar discovered the an interior-point algorithm with polynomial time.
- ▶ This discovered led to breakthroughs in quadratic programming and convex optimization, among other fields.
- ▶ Despite the polynomial-time of the interio-point method, the Simplex algorithm remains widely used.

The Linear Programming Problem

Programa Linear:

$$\begin{aligned} \max \quad & c^T x \\ \text{s.t.} \quad & Ax \leq b \\ & x \geq 0 \end{aligned}$$

Transforming \leq into $=$

$$\begin{aligned} a_1x_1 + a_2x_2 + \dots + a_nx_n &\geq b \\ &\Leftrightarrow \\ \begin{cases} a_1x_1 + a_2x_2 + \dots + a_nx_n - s = b \\ s \geq 0 \end{cases} \end{aligned}$$

Here, s is a (*slack variable*) since its value corresponds to the amount resource b which is not used.

Dealing with Real Variables

We can convert sign-unconstrained variables into nonnegative variables:

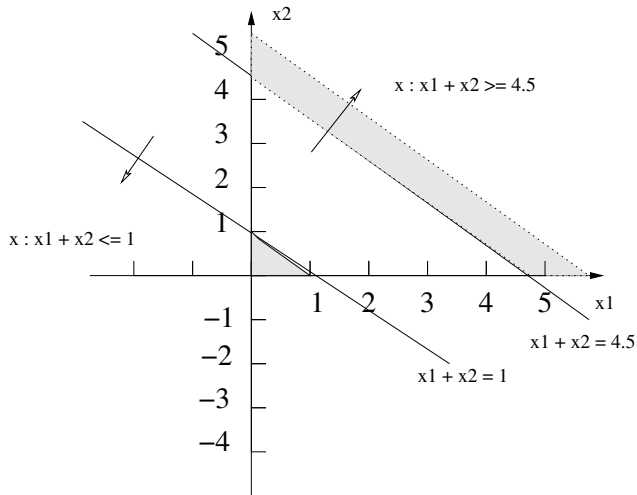
$$x \in \mathbb{R} \Leftrightarrow \begin{cases} x = x^+ - x^- \\ x^+ \geq 0 \\ x^- \geq 0 \end{cases}$$

Infeasible Problem

- ▶ A problem is said to be infeasible if there does not exist a candidate solution $x \in \mathbb{R}^n$ that meets all constraints.
- ▶ The problem below is infeasible since $S = \{x \in \mathbb{R}^n : Ax \leq b, x \geq 0\} = \emptyset$.
- ▶ Example of infeasible problem:

$$\begin{aligned} \max \quad & 5x_1 + 4x_2 \\ \text{s.t.} \quad & \\ & x_1 + x_2 \leq 1 \\ & -2x_1 - 2x_2 \leq -9 \\ & x_1, x_2 \geq 0 \end{aligned}$$

Infeasible Problem

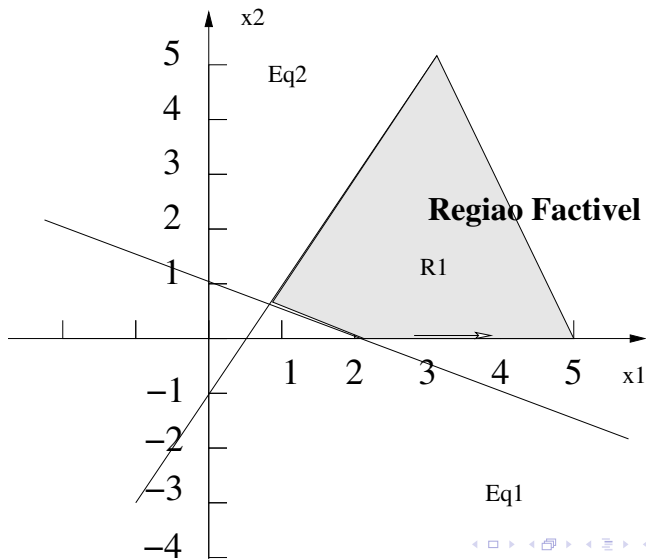


Unbounded Problem

- ▶ A problem is unbounded if there does not exist an upper bound on the value of the objective.
- ▶ In other words, the objective value can grow arbitrarily large.
- ▶ An example of unbounded problem:

$$\begin{array}{ll} \max & x_1 - 4x_2 \\ \text{s.t. :} & \\ & -2x_1 + x_2 \leq -1 \\ & -x_1 - 2x_2 \leq -2 \\ & x_1, x_2 \geq 0 \end{array}$$

Unbounded Problem



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Simplex Algorithm

History

- ▶ Proposed by George Dantzig in the 1940's.
- ▶ Today's algorithm differs from the original version.
- ▶ It is the building-block of branch-and-bound and branch-and-cut algorithms for integer programming.

Standard Problem

Linear Program:

$$\begin{aligned} \max \quad & c^T x \\ \text{s.t.} \quad & Ax = b \\ & x \geq 0 \end{aligned}$$

Simplex Algorithm,

History

- ▶ Simplex can be viewed as combinatorial search for the optimal columns of constraints matrix: columns that induce an optimal basis.
- ▶ There is an exponential number of column combinations.
- ▶ Despite this large number, Simplex is efficient in practice.

Sample Problem

Consider the following linear program:

$$\begin{aligned} \max \quad & 5x_1 + 4x_2 + 3x_3 \\ \text{s.t.} \quad & \\ & 2x_1 + 3x_2 + x_3 \leq 5 \\ & 4x_1 + x_2 + 2x_3 \leq 11 \\ & 3x_1 + 4x_2 + 2x_3 \leq 8 \\ & x_1, x_2, x_3 \geq 0 \end{aligned} \tag{1}$$

Sample Problem

After introducing slack variables, the problema assumes the form:

$$\begin{aligned} \max \quad & \delta = 0 + 5x_1 + 4x_2 + 3x_3 \\ \text{s.t. :} \quad & \\ & w_1 = 5 - 2x_1 - 3x_2 - x_3 \\ & w_2 = 11 - 4x_1 - x_2 - 2x_3 \\ & w_3 = 8 - 3x_1 - 4x_2 - 2x_3 \\ & x_1, x_2, x_3, w_1, w_2, w_3 \geq 0 \end{aligned} \quad (2)$$

Sample Problem

Dictionary

- ▶ The system (2) has the LP problem in a form known as “dictionary.”
- ▶ In the “dictionary”, the solution is given in terms of a subset of variables (*basic variables*), with cardinality equal to the number of constraints, which are given as a function of the remaining variables (*nonbasic variables*).
- ▶ The nonbasic variables assume value “zero.”
- ▶ Thus, a solution can be obtained directly from the dictionary.

Sample Problem

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Sample Problem

Dictionary (continued)

- ▶ In the above dictionary, the basis is formed by variables w_1 , w_2 and w_3 .
- ▶ The nonbasic variables are x_1 , x_2 e x_3 .
- ▶ Since nonbasic variables assume value zero, we obtain a solution from the basic variables: $w_1 = 5$, $w_2 = 11$ and $w_3 = 8$.
- ▶ The resulting solution is feasible:
 - ▶ All variables (basic and nonbasic) are nonnegative.
 - ▶ The objective function has value $\delta = 0$.

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Principles of Simplex

Iterative method

- ▶ Simplex is an iterative process that starts with a solution $y^0 = (x_1^0 \dots x_n^0 \ w_1^0 \dots w_m^0)^T$, in which $n = 3$ and $m = 3$, satisfying the equations of (1).
- ▶ Starting from (2), the Simplex seeks a new solution y^1 such that: $5x_1^1 + 4x_2^1 + 3x_3^1 > 5x_1^0 + 4x_2^0 + 3x_3^0$.
- ▶ To that end, it is necessary to bring a nonbasic variables, with a positive coefficient in the equation δ , into the basis.
- ▶ This will raise the value of the nonbasic variable entering the basis, thereby increasing the objective.

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Principles of Simplex

Iterative method (continued)

- ▶ Obviously, the variable that enters the basis cannot increase indefinitely, unless the problem is unbounded.
- ▶ The first basic variable to become zero must leave the basis, becoming nonbasic at the next iteration.
- ▶ The process is repeated until convergence to the optimum, or the problem is detected to be unbounded.

Principles of Simplex

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Simplex Algorithm: Example

Initialization

To start the iterative process, a feasible starting solution solution, such as:

$$x_1^0 = 0, x_2^0 = 0, x_3^0 = 0, w_1^0 = 5, w_2^0 = 11, w_3^0 = 8$$

This solution y^0 induces an objective value $\delta = 0$.

Simplex Algorithm: Example

Step 1

- ▶ The incumbent solution is not optimal.
- ▶ Any increase in the value of x_1 increases the o valor de δ .
- ▶ The value of x_1 cannot increase arbitrarily since it is limited by the inequalities:

$$\begin{cases} w_1 = 5 - 2x_1 \geq 0 \\ w_2 = 11 - 4x_1 \geq 0 \\ w_3 = 8 - 3x_1 \geq 0 \end{cases} \Rightarrow \begin{cases} x_1 \leq 5/2 = 2.5 \\ x_1 \leq 11/4 = 2.75 \\ x_1 \leq 8/3 = 2.667 \end{cases}$$

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Simplex Algorithm: Example

Step 1 (continued)

Thus, the value of x_1 at the next iteration should be less than $\{5/2, 11/4, 8/3\}$, which leads to:

$$x_1 = \frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}x_3 \quad (3)$$

Simplex Algorithm: Example

Step 1 (continued)

Replacing (3) in the system (2) in order to move w_1 to the right-hand side, we obtain:

$$\begin{aligned}x_1 &= \frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}x_3 \\w_2 &= 11 - 4\left(\frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}x_3\right) - x_2 - 2x_3 \\&= 1 + 2w_1 + 5x_2 \\w_3 &= 8 - 3\left(\frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}x_3\right) - 4x_2 - 2x_3 \\&= \frac{1}{2} + \frac{3}{2}w_1 + \frac{1}{2}x_2 - \frac{1}{2}x_3 \\ \delta &= 5\left(\frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}x_3\right) + 4x_2 + 3x_3 \\&= \frac{25}{2} - \frac{5}{2}w_1 - \frac{7}{2}x_2 + \frac{1}{2}x_3\end{aligned}\tag{4}$$

Simplex Algorithm: Example

Step 1 (continued)

Now, replacing equations (4) in the “dictionary” (2), the following dictionary results:

$$\begin{array}{rcll} \max & \delta & = & \frac{25}{2} - \frac{5}{2}w_1 - \frac{7}{2}x_2 + \frac{1}{2}x_3 \\ & x_1 & = & \frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}x_3 \\ & w_2 & = & 1 + 2w_1 + 5x_2 \\ & w_3 & = & \frac{1}{2} + \frac{3}{2}w_1 + \frac{1}{2}x_2 - \frac{1}{2}x_3 \end{array} \quad (5)$$

Simplex Algorithm: Example

Step 1 (continued)

- ▶ The solution induced by the dictionary (5) is $y^1 = (x_1^1, x_2^1, x_3^1, w_1^1, w_2^1, w_3^1) = (\frac{5}{2}, 0, 0, 0, 1, \frac{1}{2})$ with objective $\delta = \frac{25}{2}$.
- ▶ In this dictionary, the variables x_1 , w_2 , e w_3 are basic such that the set $\mathbb{B} = \{x_1, w_2, w_3\}$ contains all basic variables.
- ▶ The remaining variables $\mathbb{N} = \{x_2, x_3, w_1\}$ form the set of nonbasic variables.

Simplex Algorithm: Example

Step 1 (continued)

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Simplex Algorithm: Example

Step 2

- ▶ The incumbent solution is not optimal!
- ▶ Notice that a small increase in the value of x_3 will invariably increase the value of δ .
- ▶ We cannot increase the value of x_3 indefinitely because it will turn the solution infeasible — other variables may become negative.

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Simplex Algorithm: Example

Step 2 (continued)

For the solution to remain feasible, the following inequalities must be respected:

$$\begin{cases} x_1 = \frac{5}{2} - \frac{1}{2}x_3 \geq 0 \\ w_3 = \frac{1}{2} - \frac{1}{2}x_3 \geq 0 \end{cases} \Rightarrow \begin{cases} x_3 \leq 5 \\ x_3 \leq 1 \end{cases}$$

Simplex Algorithm: Example

Step 2 (continued)

- ▶ Therefore, w_3 must leave the basis so that x_3 enter the basis without violating any constraint.
- ▶ After replacing equation $x_3 = 1 + 3w_1 + x_2 - 2w_3$ in the equations of the dictionary (5), we obtain:

$$\begin{aligned}x_1 &= \frac{5}{2} - \frac{1}{2}w_1 - \frac{3}{2}x_2 - \frac{1}{2}(1 + 3w_1 + x_2 - 2w_3) \\ &= 2 - 2w_1 - 2x_2 + w_3 \\ \delta &= \frac{25}{2} - \frac{5}{2}w_1 - \frac{7}{2}x_2 + \frac{1}{2}(1 + 3w_1 + x_2 - 2w_3) \\ &= 13 - w_1 - 3x_2 - w_3\end{aligned}\tag{6}$$

Simplex Algorithm: Example

Step 2 (continued)

Replacing the equations of the dictionary (5) by the equations (6) results into a new dictionary:

$$\begin{array}{rcll} \text{Max} & \delta & = & 13 - w_1 - 3x_2 - w_3 \\ & x_1 & = & 2 - 2w_1 - 2x_2 + w_3 \\ & w_2 & = & 1 + 2w_1 + 5x_2 \\ & x_3 & = & 1 + 3w_1 + x_2 - 2w_3 \end{array} \quad (7)$$

whose basis is $\mathbb{B} = \{x_1, x_3, w_2\}$.

Simplex Algorithm: Example

Step 2 (continued)

The solution give by the dictionary (7) is optimal:

- ▶ $x_1 = 2$, $x_2 = 0$, $x_3 = 1$, $w_1 = 0$, $w_2 = 1$, $w_3 = 0$
- ▶ $\delta = 13$ is the optimal value because the coefficients of the nonbasic variables in the equation δ are all negative, in the dictionary given by (7),
- ▶ Increasing the value of any nonbasic variable will reduce the value of the objective.

Simplex Algorithm: Example

Step 2 (continued)

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Auxiliary Problem

Original Problem

$$\text{Maximize} \quad -2x_1 - x_2$$

Subject to :

$$-x_1 + x_2 \leq -1$$

$$-x_1 - 2x_2 \leq -2$$

$$x_2 \leq 1$$

$$x_1, x_2 \geq 0$$

Auxiliary Problem

Auxiliary Problem

$$\begin{array}{ll} \max & -x_0 \\ \text{s.t. :} & \\ & -x_1 + x_2 - x_0 \leq -1 \\ & -x_1 - 2x_2 - x_0 \leq -2 \\ & x_2 - x_0 \leq 1 \\ & x_0, x_1, x_2 \geq 0 \end{array}$$

Auxiliary Problem

Initial Dictionary

$$\begin{array}{rcllcl} \max & \delta & = & & -x_0 \\ & w_1 & = & -1 & +x_1 & -x_2 & +x_0 \\ & w_2 & = & -2 & +x_1 & +2x_2 & +x_0 \\ & w_3 & = & 1 & & -x_2 & +x_0 \end{array}$$

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Duality

- ▶ Associated to any linear programming problem P (primal) is another linear programming problem, the dual, which is denoted D .
- ▶ Theoretical consequences.
- ▶ Any solution for the dual D induces a limit for the optimum value of the primal P , and vice versa.

Duality

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- ▶ Theoretical consequences.
- ▶ Any solution for the dual D induces a limit for the optimum value of the primal P , and vice versa.

Motivation

Consider the sample problem:

$$\begin{aligned} P : \quad & \max && 4x_1 + x_2 + 3x_3 \\ & \text{s.t. :} && \\ & && x_1 + 4x_2 \leq 1 \\ & && 3x_1 - x_2 + x_3 \leq 3 \\ & && x_1, x_2, x_3 \geq 0 \end{aligned} \tag{8}$$

Any feasible solution to P induces a lower bound.

- ▶ For example, $x' = (1, 0, 0)$ shows that the optimum objective $\delta^* \geq 4$.
- ▶ Using the solution $x'' = (0, 0, 3)$, we discover that $\delta^* \geq 9$.

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Motivation

Issues

- ▶ Are these lower bounds close to the optimum?
- ▶ Let's multiply the first constraint of (8) by 2, multiply the second constraint by 3, and then add them up as follows:

$$\begin{array}{rcl} 2(x_1 + 4x_2) & \leq & 2(1) \\ 3(3x_1 - x_2 + x_3) & \leq & 3(3) \\ \hline 11x_1 + 5x_2 + 3x_3 & \leq & 11 \end{array}$$

- ▶ Notice that $4x_1 + x_2 + 3x_3 \leq 11x_1 + 5x_2 + 3x_3 \leq 11$, pois $x_j \geq 0$.
- ▶ Then we conclude that $9 \leq \delta^* \leq 11$.

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Motivation

- ▶ To obtain tight bound, we follow the same procedure but, this time, we use variables rather than fixed values.
- ▶ By multiplying the constraints with nonnegative variables:

$$\begin{array}{rcl} y_1(x_1 + 4x_2) & \leq & y_1 \\ y_2(3x_1 - x_2 + x_3) & \leq & 3y_2 \\ \hline (y_1 + 3y_2)x_1 + (4y_1 - y_2)x_2 + y_2x_3 & \leq & y_1 + 3y_2 \end{array}$$

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Motivation

Now, we stipulate that:

$$\begin{aligned}y_1 + 3y_2 &\geq 4 \\4y_1 - y_2 &\geq 1 \\y_2 &\geq 3 \\y_1, y_2 &\geq 0\end{aligned}\tag{9}$$

Values for (y_1, y_2) satisfying the inequalities (9) lead to the following inequalities:

$$\begin{aligned}\delta &= 4x_1 + x_2 + 3x_3 \\&\leq (y_1 + 3y_2)x_1 + (4y_1 - y_2)x_2 + y_2x_3 \\&\leq y_1 + 3y_2\end{aligned}$$

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Motivation

- ▶ We obtain an upper bound $(y_1 + 3y_2)$ for δ^* .
- ▶ We wish to minimize this upper bound:

$$\begin{aligned} D : \quad & \min \quad y_1 + 3y_2 \\ & \text{s.t. :} \\ & \quad y_1 + 3y_2 \geq 4 \\ & \quad 4y_1 - y_2 \geq 1 \\ & \quad y_2 \geq 3 \\ & \quad y_1, y_2 \geq 0 \end{aligned}$$

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Linear Programming

- ▶ Thank you for attending this lecture!!!