

# Piecewise-Linear Approximation: One Dimensional

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## Motivation

## Piecewise-Linear Models

# Summary

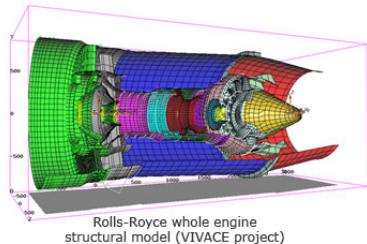
Motivation

Piecewise-Linear Models

## Surrogate Model

Engineering problems involve experiments, and simulations, to evaluate objectives and constraints which are functions of several variables.

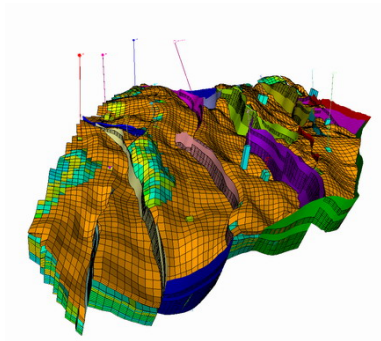
Optimal design of jet engine.



## Surrogate Model

Engineering problems involve experiments, and simulations, to evaluate objectives and constraints which are functions of several variables.

Advanced recovery of oil  
and gas reservoirs.



## *Surrogate Model*

### Challenges:

- ▶ In real-world problems, a simulation run can take several minutes, hours and even days.
- ▶ Design optimization and case studies may become impractical due to the potential need of thousands of simulations.

## Surrogate Model

### Alternative:

- ▶ Propose approximate models (“**Surrogate Models**”) that emulate the behavior of systems and simulators, however at a low computational cost.
- ▶ Surrogate Models are built from data, since the simulation model might not be known or is too complicated to be expressed in explicit form.
- ▶ Knowledge of the input-output behavior is known or given.

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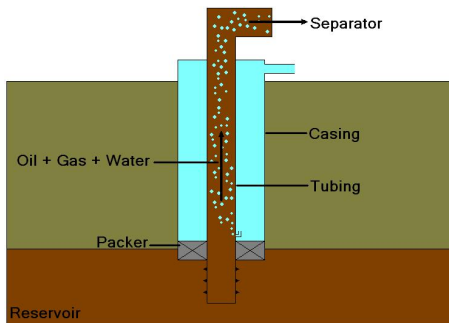
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## Surrogate Model

*“All models are wrong, the practical question is how wrong do they have to be to not be useful.” George Box*

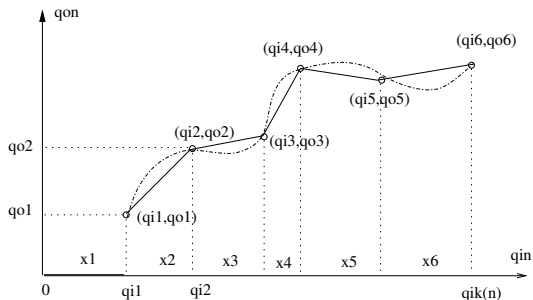
## Piecewise-Linear Approximation

Models are obtained from linear (affine) combination of input-output data:  $q_{oil}(q_{inj})$ .



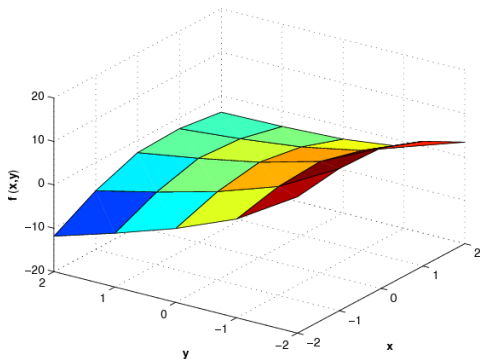
## Piecewise-Linear Approximation

- ▶ Models are obtained from linear (affine) combination of input-output data:  $q_{oil}(q_{inj})$ .
- ▶ Data:  $\{(q_{inj}^1, q_{oil}^1), (q_{inj}^2, q_{oil}^2), \dots, (q_{inj}^n, q_{oil}^n)\}$ .



## Piecewise-Linear Approximation

Function  $f(x, y)$  with a two dimensional domain.



## Piecewise-Linear Approximation

### Question:

- ▶ How does one represent piecewise-linear functions in mathematical programming?

### Several Models:

- ▶ CC (Convex Combination)
- ▶ Inc (Incremental)
- ▶ DCC (Disaggregated Convex Combination)
- ▶ Log (Logarithmic Convex Combination)
- ▶ DLog (Disaggregated Logarithmic Convex Combination)
- ▶ Multiple Choice
- ▶ SOS2 (Specially Ordered Sets of Type 2)

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Piecewise-Linear Models



## Convex Combination (CC)

**Data:**  $\{(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)\}$ .

$$x = \sum_{i=0}^n \lambda_i x_i$$

$$y = \sum_{i=0}^n \lambda_i y_i$$

$$1 = \sum_{i=0}^n \lambda_i$$

$$\lambda_i \geq 0, i = 0, \dots, n$$

$$1 = \sum_{i=1}^n z_i$$

$$z_i \in \{0, 1\}, i = 1, \dots, n$$

$$\lambda_0 \leq z_1$$

$$\lambda_i \leq z_i + z_{i+1}, i = 1, \dots, n-1$$

$$\lambda_n \leq z_n$$

**Remark:**  $z_i = 1$  if  $x \in [x_{i-1}, x_i]$ .

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**Remark:**  $z_i = 1$  if  $x \in [x_{i-1}, x_i]$ .

## Incremental (INC)

**Givens:**  $\{(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)\}$ .

$$x = x_0 + \sum_{i=1}^n \delta_i$$

$$y = y_0 + \sum_{i=1}^n \frac{(y_i - y_{i-1})}{(x_i - x_{i-1})} \delta_i$$

$$\delta_1 \leq (x_1 - x_0)$$

$$\delta_i \leq (x_i - x_{i-1})z_{i-1}, \quad i = 2, \dots, n$$

$$\delta_i \geq (x_i - x_{i-1})z_i, \quad i = 1, \dots, n-1$$

$$\delta_n \geq 0$$

$$z_i \in \{0, 1\}, \quad i = 1, \dots, n-1$$

**Remarks:**

- ▶ If  $z_i = 1$ , then  $z_j = 1$  for  $j = 1, \dots, i-1$ .
- ▶ If  $z_i = 1$ , then  $\delta_i = (x_i - x_{i-1})$ .

# Disaggregated Convex Combination (DCC)

**Givens:**  $\{(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)\}$ .

$$x = \sum_{i=1}^n (\lambda_i^L x_{i-1} + \lambda_i^R x_i)$$

$$y = \sum_{i=1}^n (\lambda_i^L y_{i-1} + \lambda_i^R y_i)$$

$$\lambda_i^L, \lambda_i^R \geq 0, \quad i = 1, \dots, n$$

$$z_i = \lambda_i^L + \lambda_i^R, \quad i = 1, \dots, n$$

$$1 = \sum_{i=1}^n z_i$$

$$z_i \in \{0, 1\}, \quad i = 1, \dots, n$$

## Logarithmic Disaggregated Convex Combination (DLog)

Consists of a logarithmic encoding of the binary variables  $y_i$ , which correspond to intervals.

$i$	$\delta_3\delta_2\delta_1$
1	000
2	001
3	010
4	011
5	100
6	101
7	110
8	111

Let:

- ▶  $B_j^0 = \{i : \text{code of } i \text{ has value 0 at position } j\}.$
- ▶  $B_j^1 = \{i : \text{code of } i \text{ has value 1 at position } j\}.$

Example:

- ▶  $B_1^0 = \{1, 3, 5, 7\}.$
- ▶  $B_2^1 = \{3, 4, 7, 8\}.$

## Logarithmic Disaggregated Convex Combination (DLog)

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$$\lambda_i^L, \lambda_i^R \geq 0, i = 1, \dots, n$$

$$\sum_{i=1}^n (\lambda_i^L + \lambda_i^R) = 1,$$

$$\lambda_i^L + \lambda_i^R \leq \delta_j, i \in B_j^1, j = 1, \dots, \lceil \log_2 n \rceil,$$

$$\lambda_i^L + \lambda_i^R \leq 1 - \delta_j, i \in B_j^0, j = 1, \dots, \lceil \log_2 n \rceil,$$

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## DCC e DLog

### Remarks:

- ▶ DLog has the same number of continuous variables and constraints of DCC.
- ▶ However DLog needs a logarithmic number of binary variables.



## SOS2

A set of variables, let us say  $\{\lambda_0, \dots, \lambda_n\}$ , is SOS2 (**S**pecial **O**rdered **S**et of **V**ariables **T**ype 2) if:

1. At most two variables are positive.
2. If two variables are positive, then they are consecutive in the ordered set, let us say  $\lambda_j$  and  $\lambda_{j+1}$ .

## Piecewise-Linear Model Based on SOS2

**Givens:**  $\{(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)\}$ .

$$x = \sum_{i=0}^n \lambda_i x_i$$

$$y = \sum_{i=0}^n \lambda_i y_i$$

$$1 = \sum_{i=0}^n \lambda_i$$

$$\lambda_i \geq 0, i = 0, \dots, n$$

$\{\lambda_i\}_{i=0}^n$  is SOS2

## How Does SOS2 Work?

Implemented directly by the optimization solver:

- ▶ Suppose that  $\{\lambda_0, \dots, \lambda_n\}$  is a SOS2 set.
- ▶ Let  $\{\tilde{\lambda}_0, \dots, \tilde{\lambda}_n\}$  be the incumbent solution, in which  $\tilde{\lambda}_{k_1}, \tilde{\lambda}_{k_2} > 0$  for  $k_1, k_2 \in \{0, \dots, n\}$ ,  $k_1 < k_2$ , and  $k_2 - k_1 \geq 2$ .

The infeasibility can be ruled out by "branching":

- ▶ Constraint  $\lambda_0 = \dots = \lambda_{k_1} = 0$  on the left branch.
- ▶ Constraint  $\lambda_{k_1+2} = \dots = \lambda_n = 0$  on the right branch.

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## Logarithmic Convex Combination (Log)

### Remarks:

- ▶ Version of the CC model with a logarithmic number of variables and constraints.
- ▶ Needs an encoding corresponding to a Gray-Code.
- ▶ Complex structure of constraints, particularly in multidimensional domains.
- ▶ Requires a domain partitioning given by a  $J-1$  triangulation.

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## Log Model: Example

Let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be a function with a piecewise-linear model:

- ▶ Set of breakpoints:  $\mathcal{X} = \{x_0, x_1, \dots, x_n\}$ .
- ▶ Set of function values:  $\mathcal{Y} = \{y_j = f(x_j) : x_j \in \mathcal{X}\}$ .

Implementation:

- ▶ Set of domain intervals:  $\mathcal{I} = \{i_1, \dots, i_n\}$ , such that
  - ▶  $i_1 = [x_0, x_1]$ ,  $i_2 = [x_1, x_2]$ ,  $\dots$ ,  $i_n = [x_{n-1}, x_n]$ .
- ▶  $B : \mathcal{I} \rightarrow \{0, 1\}^{\log_2 |\mathcal{I}|}$  is a bijection defining a "Gray Code:"
  - ▶  $B(i)$  differs from  $B(i + 1)$  by just one bit.

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## Log Model: Example

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$$B(i_1) = B([x_0, x_1]) = (0, 0, 0)$$

$$B(i_2) = B([x_1, x_2]) = (0, 0, 1)$$

$$B(i_3) = B([x_2, x_3]) = (0, 1, 1)$$

$$B(i_4) = B([x_3, x_4]) = (0, 1, 0)$$

$$B(i_5) = B([x_4, x_5]) = (1, 1, 0)$$

$$B(i_6) = B([x_5, x_6]) = (1, 0, 0)$$

$$B(i_7) = B([x_6, x_7]) = (1, 0, 1)$$

$$B(i_8) = B([x_7, x_8]) = (1, 1, 1)$$

---

## Log Model: Example

Let  $J^+(B, l) \subseteq \mathcal{X}$  be the subset of breakpoints such that:

- ▶ for each  $x \in J^+(B, l)$ , the interval  $I(x) \in \mathcal{I}$  to which it belongs, has value 1 at position  $l$  of the binary code  $B(I(x))$ .

Let  $J^0(B, l) \subseteq \mathcal{X}$  be the subset of breakpoints such that:

- ▶ for each  $x \in J^0(B, l)$ , the interval  $I(x) \in \mathcal{I}$  to which it belongs, has value 0 at position  $l$  of binary code  $B(I(x))$ .

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## Log Model: Example

For  $l = 1$ :

$$J^+(B, 1) = \{x_2, x_7, x_8\}$$

$$J^0(B, 1) = \{x_0, x_4, x_5\}$$

For  $l = 2$ :

$$J^+(B, 2) = \{x_3, x_4, x_8\}$$

$$J^0(B, 2) = \{x_0, x_1, x_6\}$$

For  $l = 3$ :

$$J^+(B, 3) = \{x_5, x_6, x_7, x_8\}$$

$$J^0(B, 3) = \{x_0, x_1, x_2, x_3\}$$

**Remark:** This structure leads to a "branching scheme" compatible with SOS2.

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## CC Model

$$f = \sum_{v \in \mathcal{V}} f(v) \lambda_v, \quad x = \sum_{v \in \mathcal{V}} v \lambda_v, \quad (1)$$

$$1 = \sum_{v \in \mathcal{V}} \lambda_v, \quad (2)$$

$$\lambda_v \leq \sum_{P \in \mathcal{P}(v)} y_P, \quad 1 = \sum_{P \in \mathcal{P}} y_P, \quad (3)$$

$$\lambda_v \geq 0, v \in \mathcal{V}, \quad (4)$$

$$y_P \in \{0, 1\}, P \in \mathcal{P} \quad (5)$$

**Remark:** The Log models offers a logarithmic representation of the equations (3) e (5).

## Log Model

$$f = \sum_{v \in \mathcal{V}} f(v) \lambda_v, \quad (6)$$

$$x = \sum_{v \in \mathcal{V}} v \lambda_v, \quad (7)$$

$$\mathbf{1} = \sum_{v \in \mathcal{V}} \lambda_v, \quad (8)$$

$$\lambda_v \geq 0, v \in \mathcal{V}, \quad (9)$$

$$\sum_{v \in J^+(B, l)} \lambda_v \leq y_l, l \in \{1, \dots, \lceil \log_2 |\mathcal{I}| \rceil\}, \quad (10)$$

$$\sum_{v \in J^0(B, l)} \lambda_v \leq (1 - y_l), l \in \{1, \dots, \lceil \log_2 |\mathcal{I}| \rceil\}, \quad (11)$$

$$y_l \in \{0, 1\}, l \in \{1, \dots, \lceil \log_2 |\mathcal{I}| \rceil\}. \quad (12)$$

## Piecewise-Linear Approximation: One Dimensional

- ▶ End!
- ▶ Thank you for your attention.